Stephanie Hofmann & Bobby Neuhold

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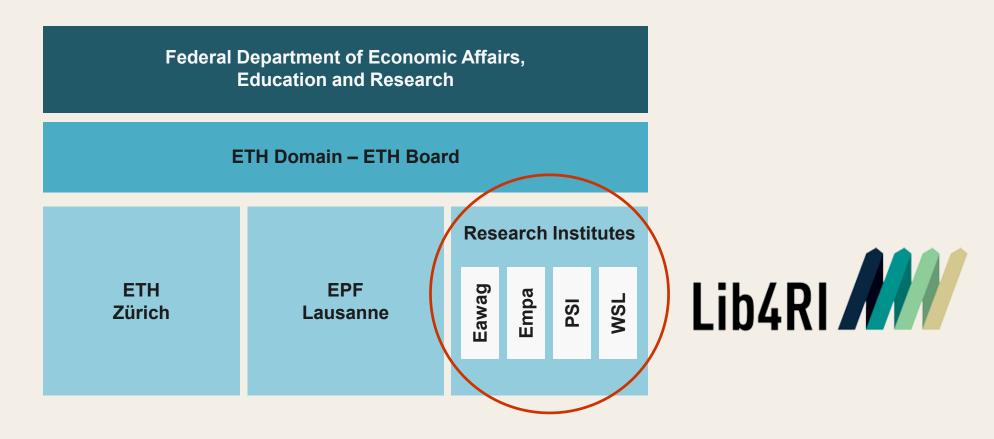
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Lib4RI: PSI



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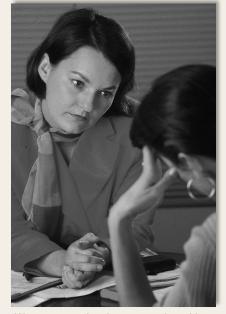




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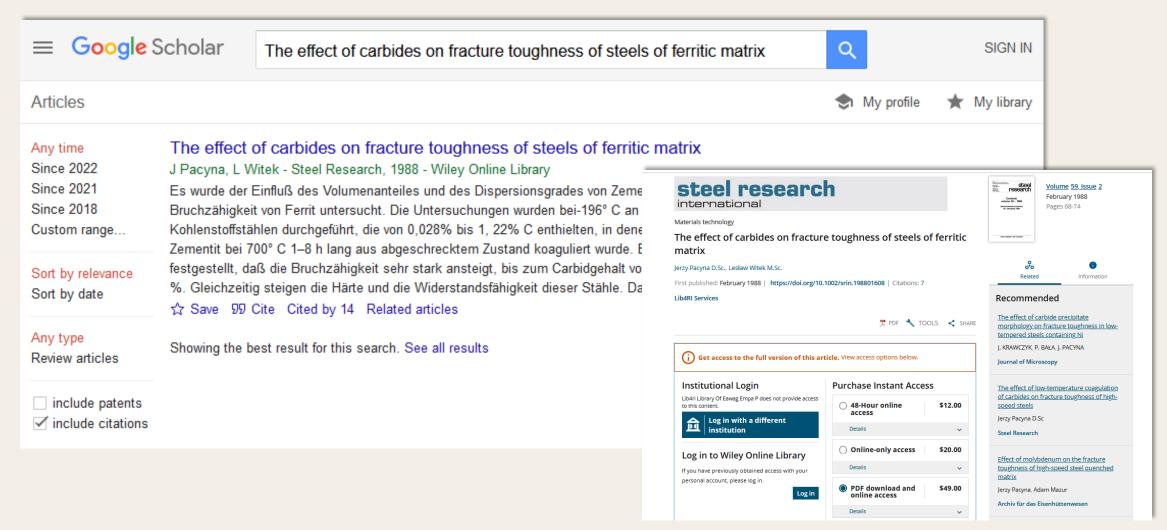
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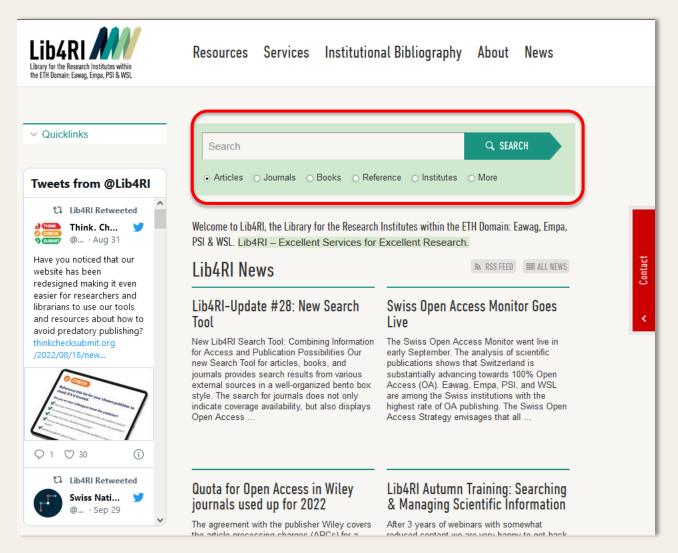


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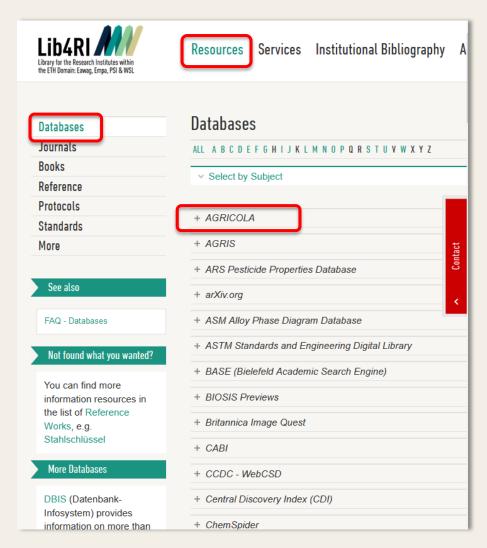


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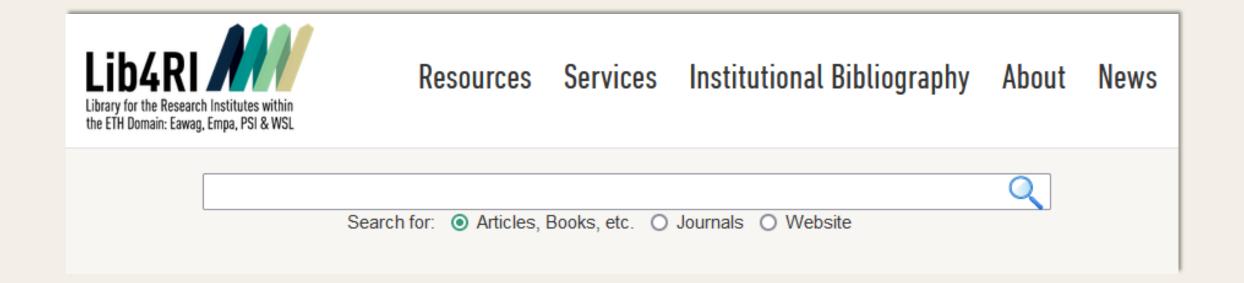
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- 2. Arvantis, L.G. and G.W. Fowler. (1979) "Some Aspects of Biased Sampling Estimators." Forest Resource Inventories Workshop Proceedings, Vol. 1, Fort Collins, 298-309.
- 3. Kahru A. Ecotoxicological tests in non-ecotoxicological research: Contribution to 3Rs. Use of luminescent photobacteria for evaluating the toxicity of 47 MEIC reference chemicals. ALTEX. 2006;23:302–308.
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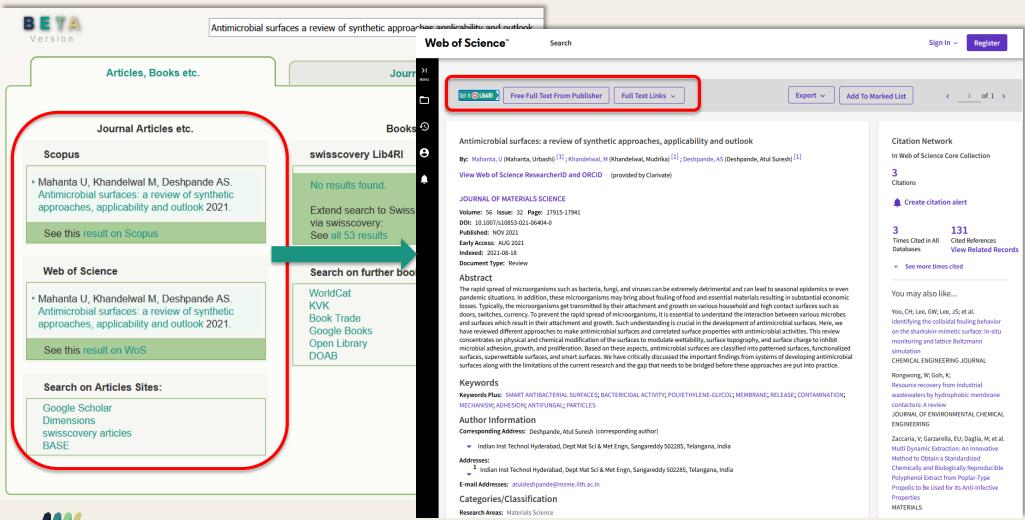
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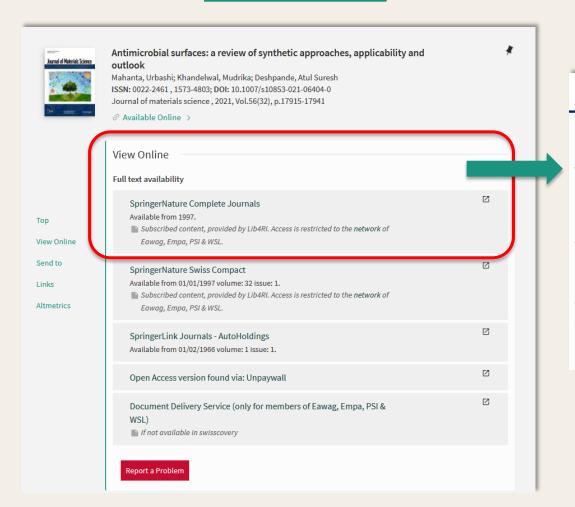
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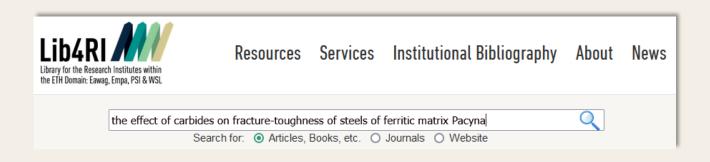


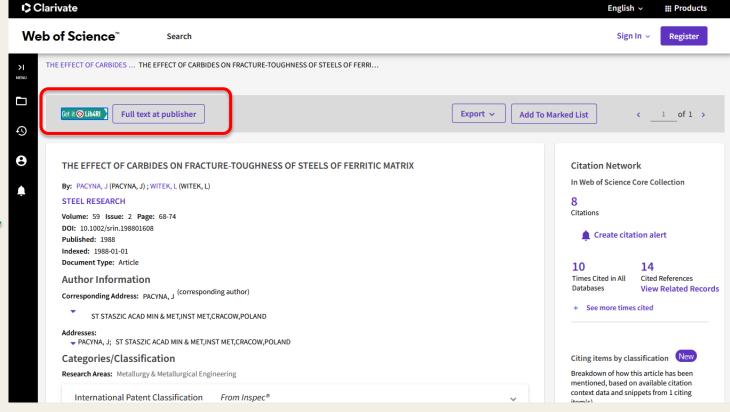




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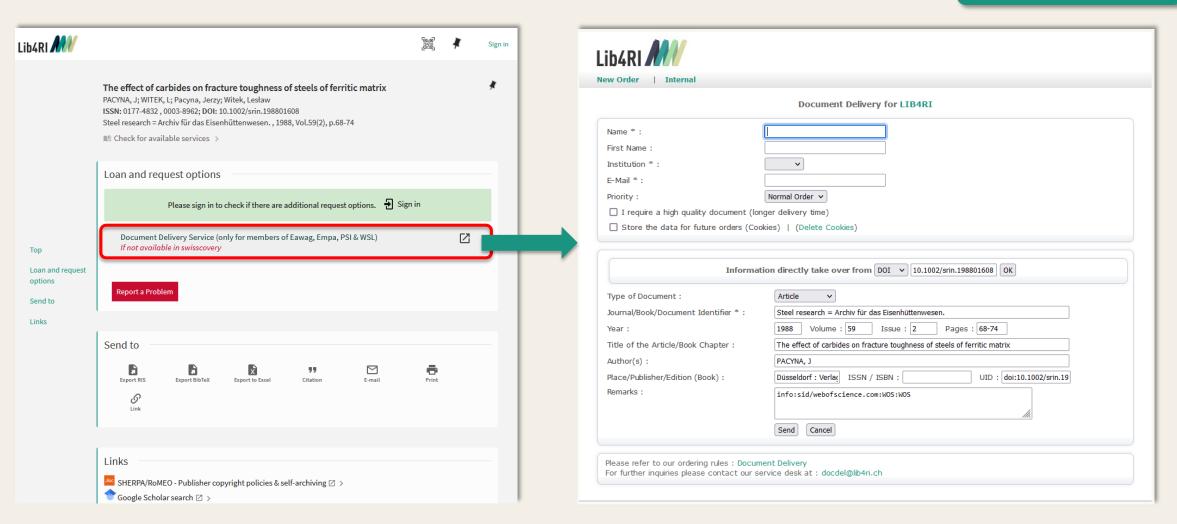






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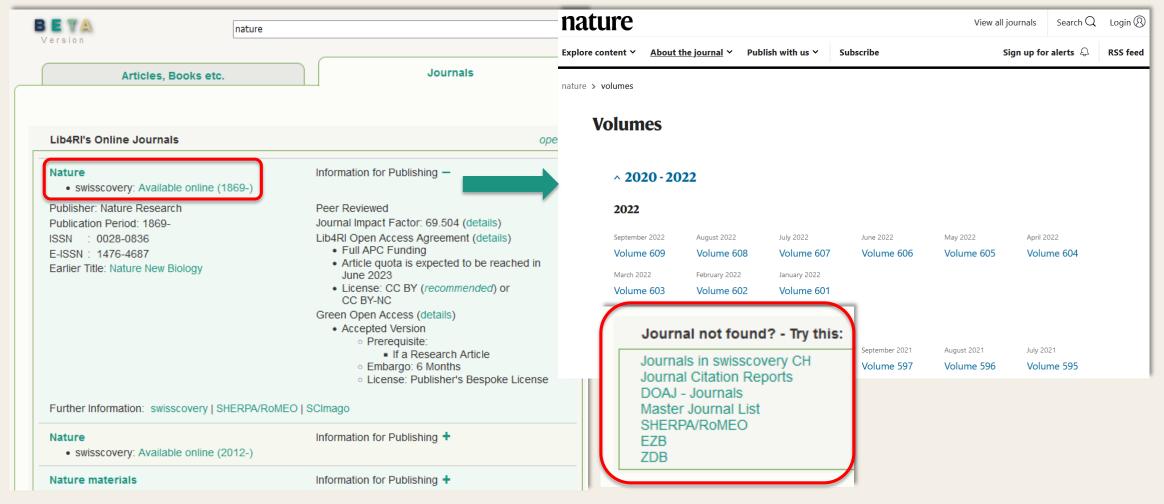






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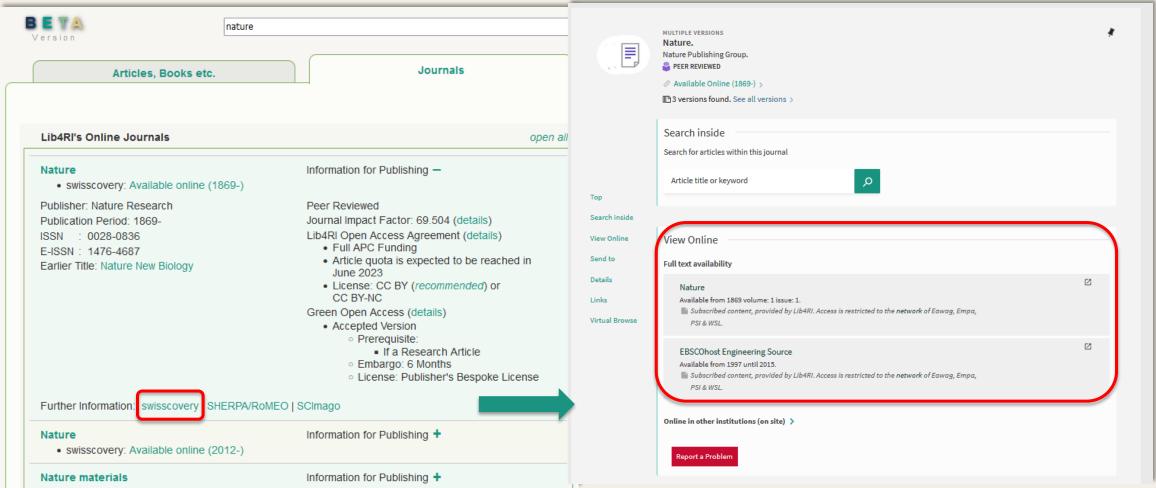






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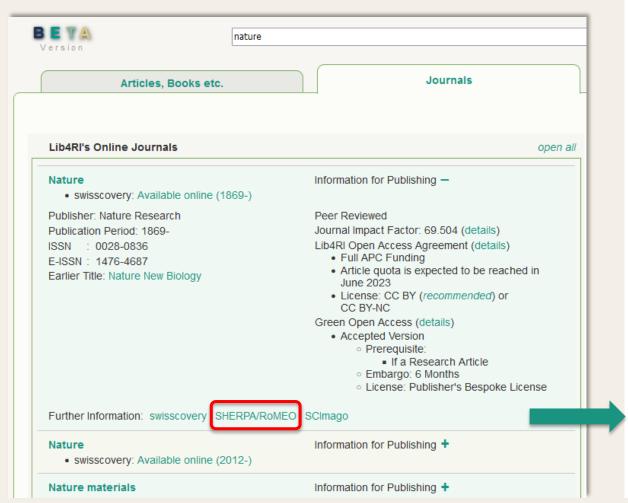


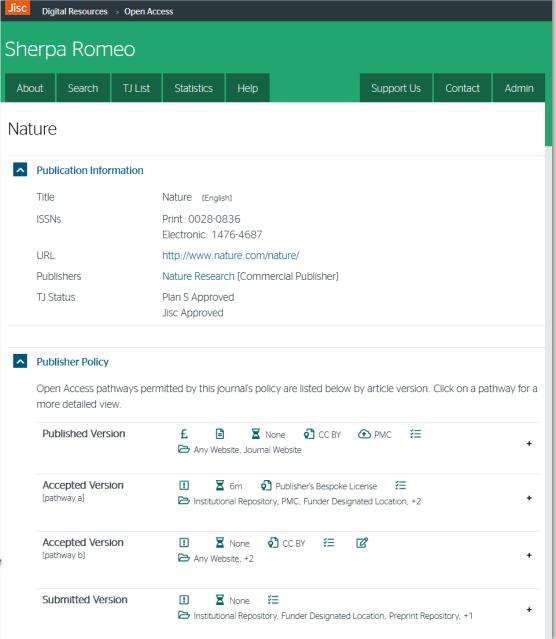






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[5] L. Simonot, G. Maire, A comparative study of LaCoO3, Co3O4 and LaCoO3—Co3O4: I. Preparation, characterisation and catalytic properties for the oxidation of CO, Appl. Catal. B: Environ. 11 (2) (1997) 167_179

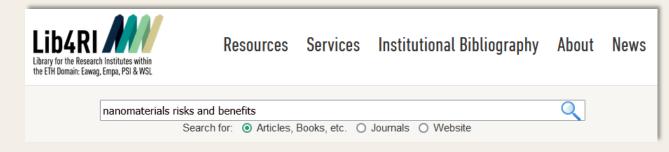
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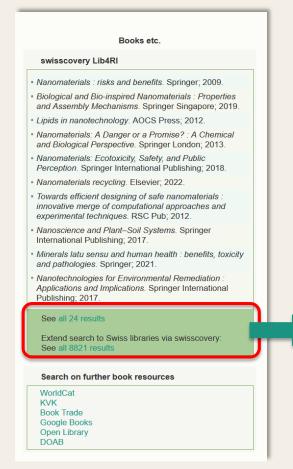
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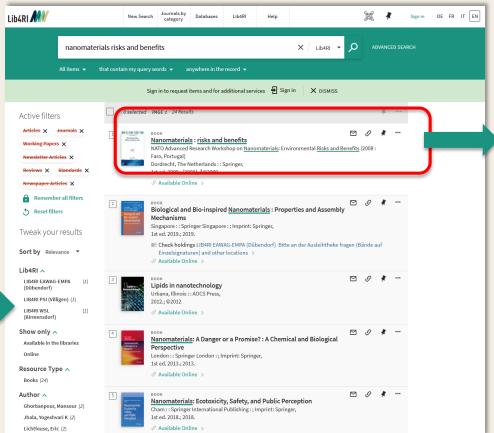
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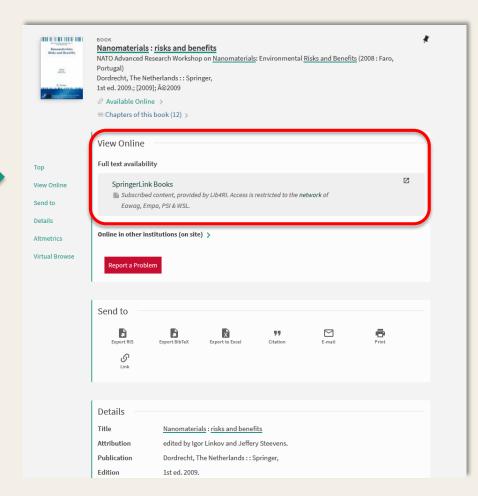


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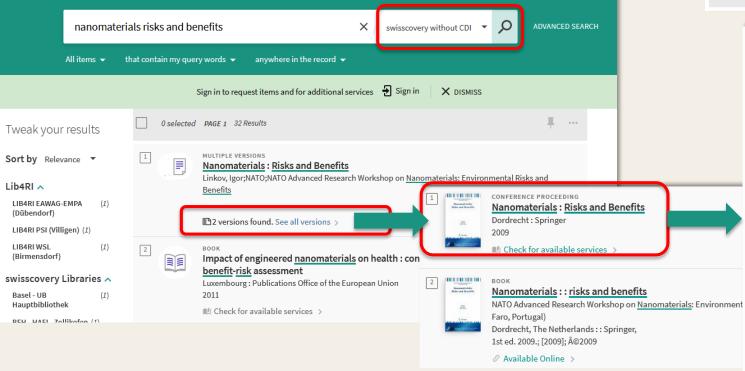






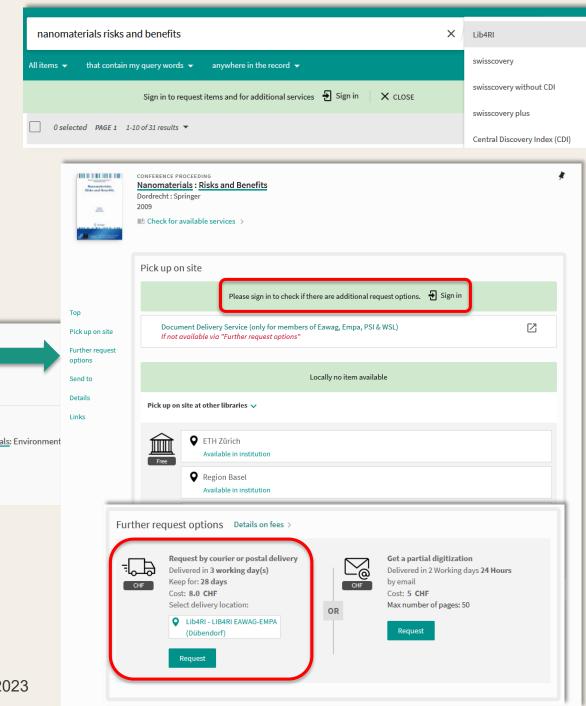


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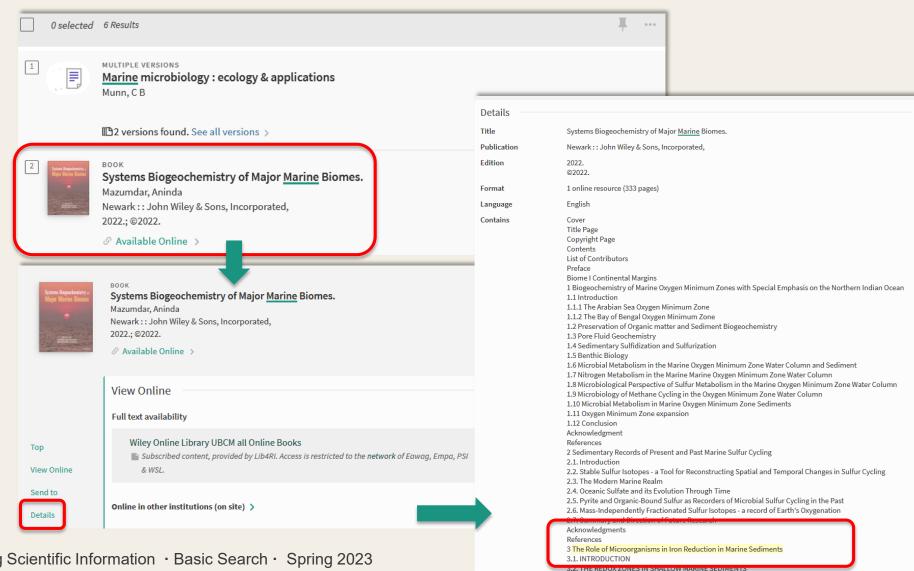




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Reyes, C. and Meister, P. (2022). The Role of Microorganisms in Iron Reduction in Marine Sediments. In Systems Biogeochemistry of Major Marine Biomes (eds A. Mazumdar and W. Ghosh).

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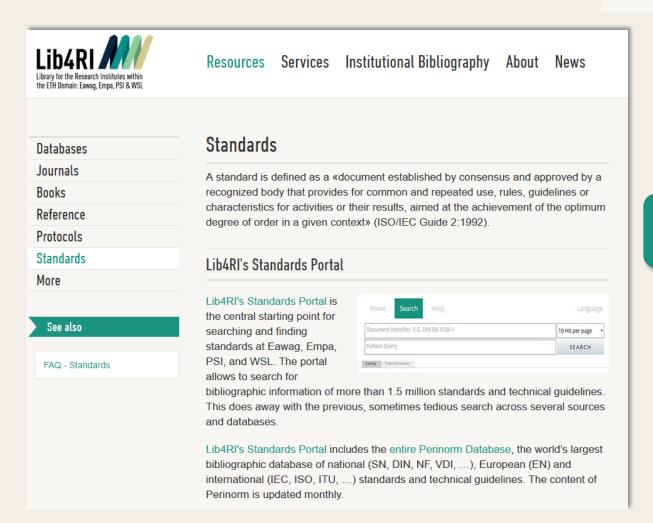
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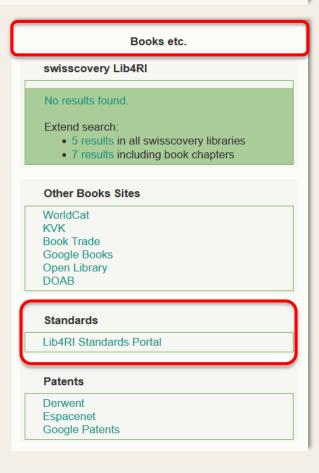
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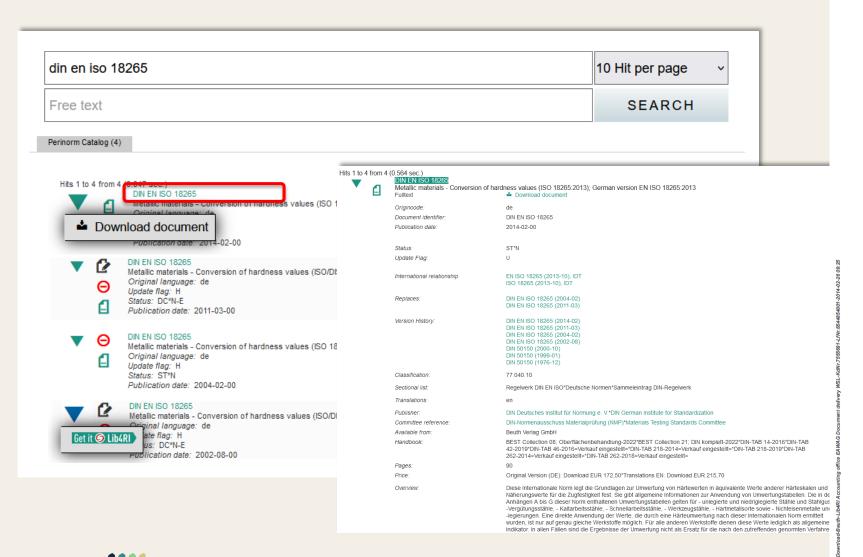




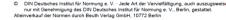
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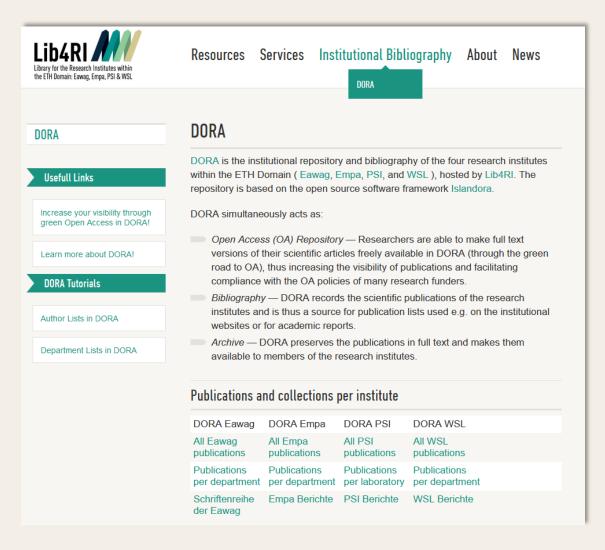


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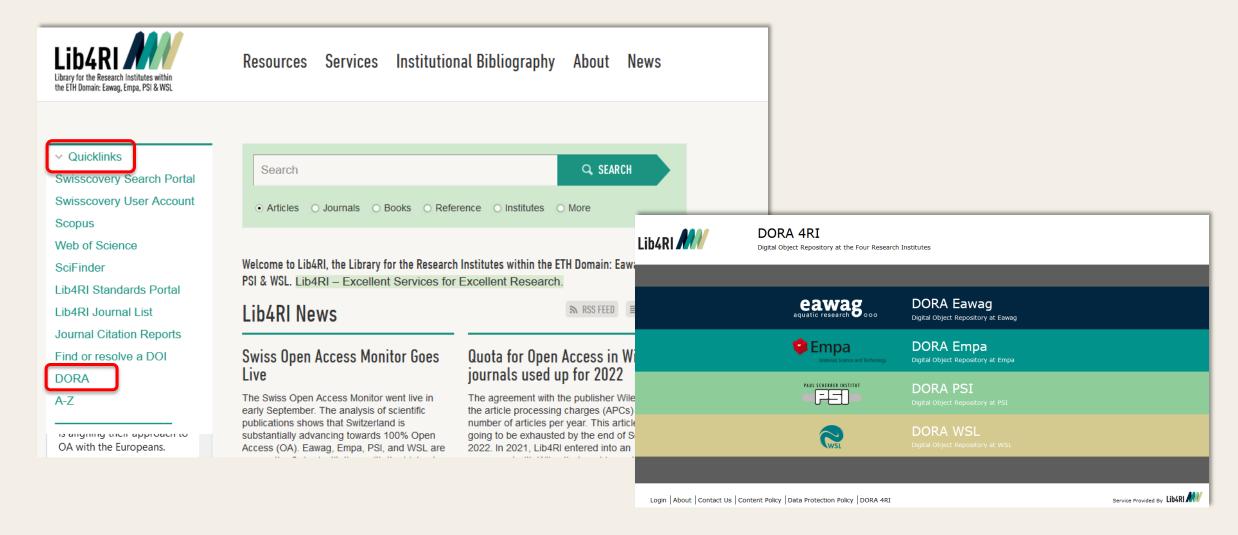


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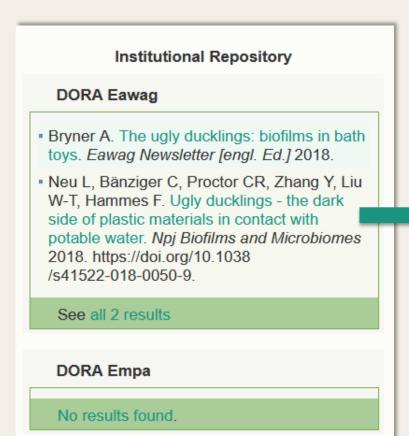
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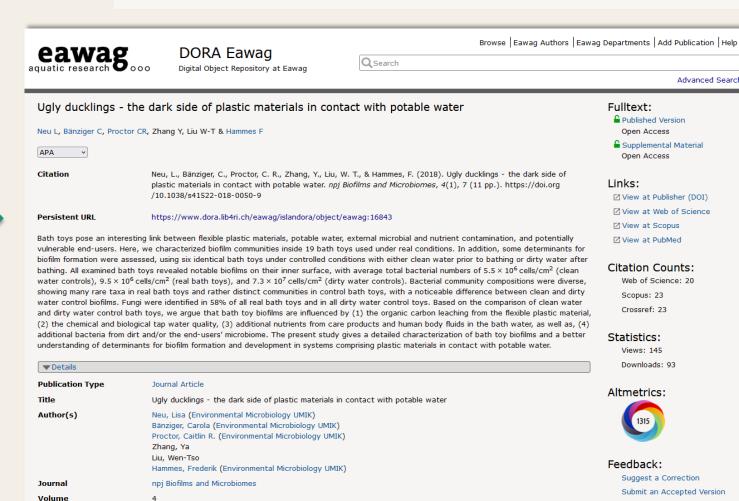
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review on self-healing polymers for soft robotics. Materials Today, 47, 187-205. https://doi.org/10.1016

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The intrinsic compliance of soft robots provides safety, a natural adaptation to its environment, allows to absorb shocks, and protects them against mechanical impacts. However, a literature study shows that the soft polymers used for their construction are susceptible to various types of damage, including fatigue, overloads, interfacial debonding, and cuts, tears and perforations by sharp objects. An economic and ecological solution is to construct future soft robotic systems out of self-healing polymers, incorporating the ability to heal damage. This review paper proposes criteria to evaluate the potential of a self-healing polymer to be used in soft robotic applications. Based on these soft robotics requirements and on defined performance parameters of the materials, linked to the mechanical and healing properties, the different types of self-healing polymers already available in literature are critically assessed and compared. In addition to a description of the state of the art on self-healing soft robotics, the paper discusses the driving forces and limitations to spur the interdisciplinary combination between self-healing polymer science and soft robotics.

▼ Details

Publication Type

Journal Article

Title A review on self-healing polymers for soft robotics

Author(s)

Terryn, Seppe Langenbach, Jakob Roels, Ellen Brancart, Joost Bakkali-Hassani, Camille Poutrel, Quentin-Arthur

Georgopoulou, Antonia (201 High Performance Ceramics)

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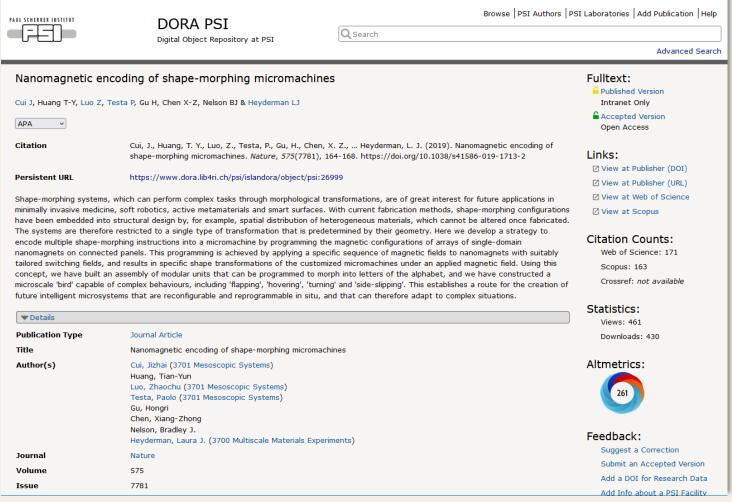
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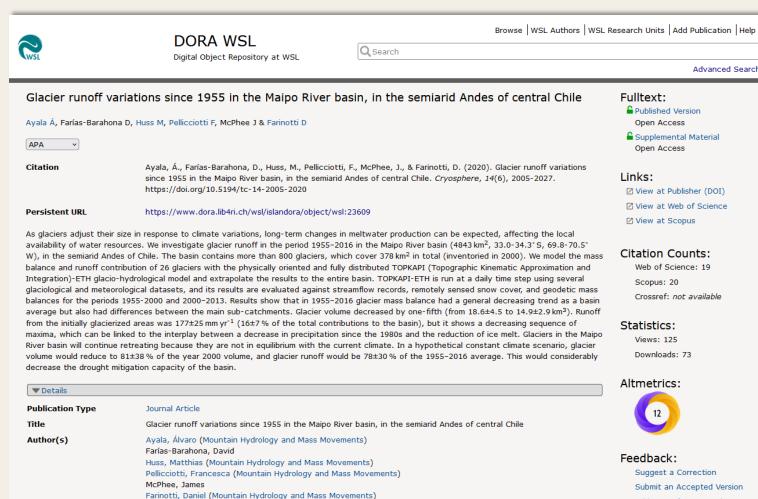
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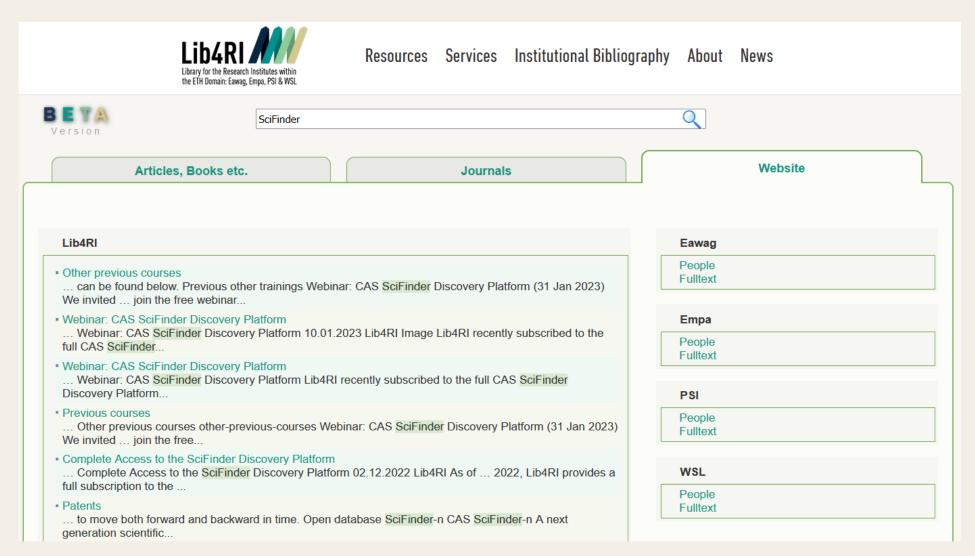
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Sometimes free web resources can be ineffective for searching. Then, the licensed databases «Derwent Innovation Index» (interdisciplinary) and «SciFinder-n» (chemistry) may be better suited.

+ Derwent Innovation Index

+ SciFinder-n

Technology Transfer

Further assistance on searching and finding patents can be obtained from InfoServices.

Please note: If you are searching patents in preparation for applying for a patent yourself, you should contact the departments for technology transfer at the PSI or Eawag-Empa:

Eawag-Empa Technology Transfer:

Marlen Müller Tel. 058 765 41 97 marlen.mueller@empa.ch

PSI — Technology Transfer: John Millard

Tel. 056 310 41 83 techtransfer@psi.ch



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Thanks for your interest, keep being curious!

Stephanie Hofmann & Bobby Neuhold
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Überlandstrasse 133 • 8600 Dübendorf
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